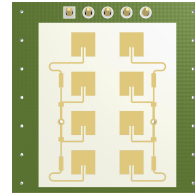


## Features

- 24 GHz K-band miniature I/Q transceiver
- 140MHz sweep FM input
- 2 x 4 patch antenna
- 2 balanced mixer with 50MHz bandwidth
- Excellent noise cancelling ability though I/Q technology
- Beam aperture 80°/34°
- 15dBm EIRP output power
- 25x25mm<sup>2</sup> surface, <6.5mm thickness
- Lowcost design



K-LC2 Actual Size

## Applications

- Direction sensitive movement detectors
- Security systems
- Object speed measurement systems
- Simple ranging detection using FSK
- Industrial sensors

## Description

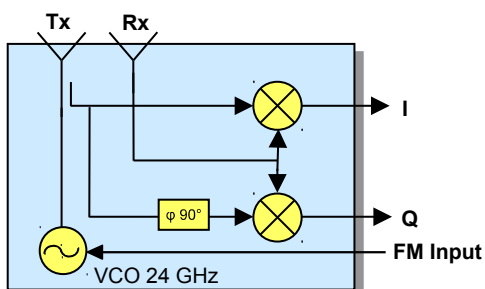
K-LC2 is a 2 x 4 patch Doppler module with an asymmetrical beam for lowcost short distance applications. Its typical applications are movement sensors in the security and presence detection domain.

In building automation this module may be an alternative for infrared PIR or AIR systems thanks to its outstanding performance/cost ratio.

The module is extremely small and lightweight. With its IF bandwidth from DC to 50MHz it opens many new applications. FSK is possible thanks to the unique RFbeam oscillator design. This allows to use this lowcost module even in ranging applications.

Powerful starterkits (ST100 and ST200) with signal conditioning and visualization on the PC's are available.

## Blockdiagram



## K-LC2 RADAR TRANSCEIVER

## Datasheet

## Characteristics

Parameter	Conditions / Notes	Symbol	Min	Typ	Max	Unit
<b>Operating conditions</b>						
Supply voltage		$V_{cc}$	4.75	5.0	5.25	V
Supply current	VCO Pin open	$I_{cc}$		35	45	mA
VCO input voltage		$U_{vco}$	-0.5		2.0	V
VCO pin resistance	Driving voltage source <sup>Note 1</sup>	$R_{vco}$		570		$\Omega$
Operating temperature		$T_{op}$	-20		+60	$^{\circ}\text{C}$
Storage temperature		$T_{st}$	-20		+80	$^{\circ}\text{C}$
<b>Transmitter</b>						
Transmitter frequency	VCO pin left open, $T_{amb} = -20^{\circ}\text{C} \dots +60^{\circ}\text{C}$	$f_{TX}$	24.050	24.125	24.250	GHz
Frequency drift vs temperature	$V_{cc} = 5.0\text{V}$ , $-20^{\circ}\text{C} \dots +60^{\circ}\text{C}$ <sup>Note 2</sup>	$\Delta f_{TX}$		-0.9		MHz/ $^{\circ}\text{C}$
Frequency tuning range		$\Delta f_{vco}$		140		MHz
VCO sensitivity		$S_{vco}$		-55		MHz/V
VCO Modulation Bandwidth	$\Delta f = 20\text{MHz}$	$B_{vco}$		3		MHz
Output power	EIRP	$P_{TX}$	+12	+15	+17	dBm
Output power deviation	Full VCO tuning range	$\Delta P_{TX}$			+/- 1	dBm
Spurious emission	According to ETSI 300 440	$P_{spur}$			-30	dBm
Turn-on time	Until oscillator stable, $\Delta f_{TX} < 5\text{MHz}$	$t_{on}$		1		$\mu\text{s}$
<b>Receiver</b>						
Mixer Conversion loss	$f_{IF} = 1\text{kHz}$ , IF load = $1\text{k}\Omega$	$D_{mixer1}$		-6		dB
	$f_{IF} = 20\text{MHz}$ , IF load = $50\Omega$	$D_{mixer2}$		-11		dB
Antenna Gain	$F_{TX} = 24.125\text{GHz}$ <sup>Note 3</sup>	$G_{Ant}$		8.6		dB
Receiver sensitivity	$f_{IF} = 500\text{Hz}$ , $B = 1\text{kHz}$ , $R_{IF} = 1\text{k}\Omega$ , $S/N = 6\text{dB}$	$P_{RX1}$		-96		dBm
	$f_{IF} = 1\text{MHz}$ , $B = 20\text{MHz}$ , $R_{IF} = 50\Omega$ , $S/N = 6\text{dB}$	$P_{RX1}$		-84		dBm
Overall sensitivity	$f_{IF} = 500\text{Hz}$ , $B = 1\text{kHz}$ , $R_{IF} = 1\text{k}\Omega$ , $S/N = 6\text{dB}$	$D_{system}$		-111		dBc
<b>IF output</b>						
IF output resistance		$R_{IF}$		50		$\Omega$
IF frequency range	-3dB Bandwidth, IF load = $50\Omega$	$f_{IF}$	0		50	MHz
IF noise power	$f_{IF} = 500\text{Hz}$ , IF load = $50\Omega$	$P_{IFnoise1}$		-134		dBm/Hz
	$f_{IF} = 1\text{MHz}$ , IF load = $50\Omega$	$P_{IFnoise2}$		-164		dBm/Hz
IF noise voltage	$f_{IF} = 500\text{Hz}$ , IF load = $1\text{k}\Omega$	$U_{IFnoise1}$		-147		dBV/Hz
	$f_{IF} = 500\text{Hz}$ , IF load = $1\text{k}\Omega$	$U_{IFnoise1}$		45		nV/ $\sqrt{\text{Hz}}$
IF output offset voltage	Full VCO range, no object in range	$U_{IF}$	-200		200	mV
I/Q amplitude balance	$f_{IF} = 500\text{Hz}$ , $U_{IF} = 1\text{mVpp}$	$\Delta U_{IF}$		3		dB
I/Q phase shift	$f_{IF} = 1\text{Hz} - 20\text{kHz}$	$\varphi$	80	90	100	$^{\circ}$
Supply rejection	Rejection supply pins to IF output	$D_{supply}$		25		dB

K-LC2 RADAR TRANSCEIVER

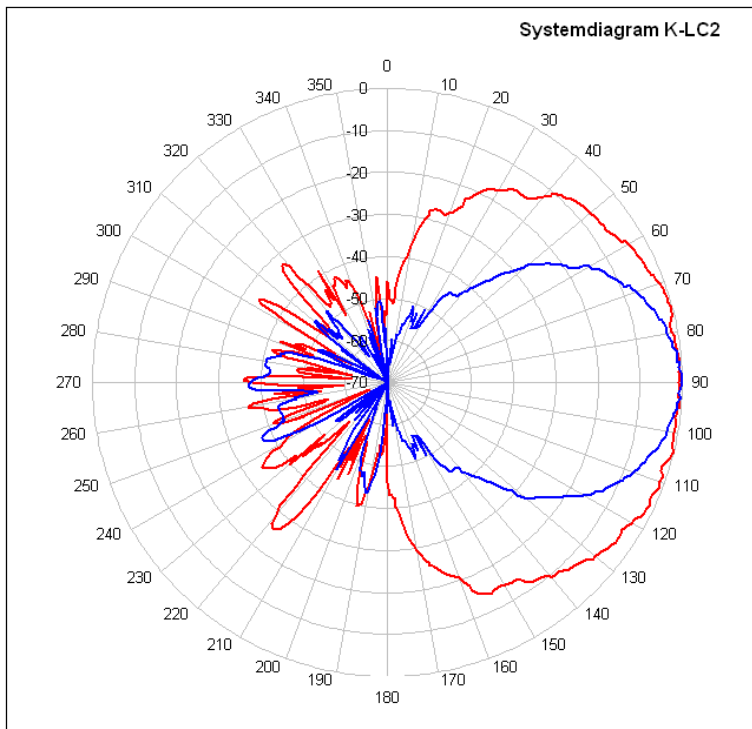
Datasheet

Parameter	Conditions / Notes	Symbol	Min	Typ	Max	Unit
<b>Antenna</b>						
Horizontal -3dB beamwidth	E-Plane	$W_e$		80		°
Vertical -3dB beamwidth	H-Plane	$W_h$		34		°
Horiz. sidelobe suppression		$D_e$	-12	-20		dB
Vertical sidelobe suppression		$D_h$	-12	-20		dB
<b>Body</b>						
Outline Dimensions				25*25*6		mm <sup>3</sup>
Weight				4.5		g
Connector	5pin single row jumper					

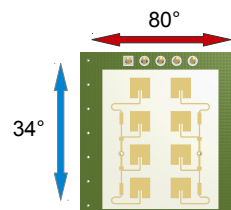
- Note 1 The VCO input has an internal voltage source with approx. 0.9VDC. For driving this pin it is necessary to source and sink current
- Note 2 Transmit frequency stays within 24.050 to 24.250GHz over the specified temperature range when the VCO pin is left open
- Note 3 Theoretical value, given by Design

Antenna System Diagram

This diagram shows module sensitivity in both azimuth and elevation directions. It incorporates therefore the transmitter and receiver antenna characteristics.



Horizontal 80° , vertical 34°  
at IF output voltage -6dB  
(corresponds to -3dB Tx power)



Remarks:  
The broader the antenna, the narrower the beam.

Fig. 2: System diagram

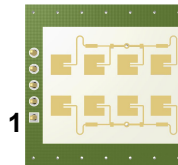
## FM Characteristics

VCO Voltage generates an output signal even without an object in range because of the finite isolation between transmitter and receiver path. This effect is called self-mixing and leads to a DC signal that depends on the carrier frequency.

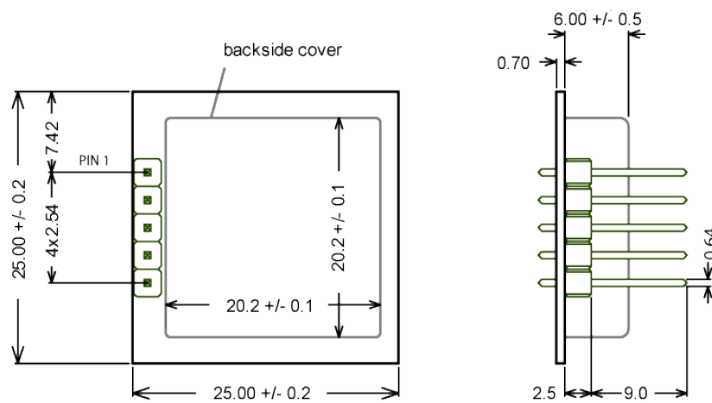
Mixer offset voltages are also dependent on production tolerances.

## Pin Configuration

Pin	Description	Typical Value
1	IF Q output	load 1kOhm
2	VCC	5VDC supply
3	IF I output	load 1kOhm
4	GND	ground
5	VCO in	Open = $f_0$



## Outline Dimensions



All Dimensions in mm; values are typical unless otherwise specified

**Fig. 3: Mechanical data**

## Application Notes

### Sensitivity and Maximum Range

The values indicated here are intended to give you a 'feeling' of the attainable detection range with this module. It is not possible to define an exact RCS (radar cross section) value of real objects because reflectivity depends on many parameters. The RCS variations however influence the maximum range only by  $\sqrt[4]{\sigma}$ .

Maximum range for Doppler movement depends mainly on:

- Module sensitivity	S:	-111dBc (@0.5kHz IF Bandwidth)
- Carrier frequency	f <sub>0</sub> :	24.125GHz
- Radar cross section RCS ("reflectivity") of the object	σ <sup>1)</sup> :	1m <sup>2</sup> approx. for a moving person >50m <sup>2</sup> for a moving car

note <sup>1)</sup> RCS indications are very inaccurate and may vary by factors of 10 and more.

The famous "Radar Equation" may be reduced for our K-band module to the following relation:

$$r = 0.0167 \cdot 10^{\frac{-s}{40}} \cdot \sqrt[4]{\sigma}$$

Using this formula, you get an indicative detection range of

- >10 meters for a moving person.
- >26m meters for a moving car

Please note, that range values also highly depend on the performance of signal processing, environment conditions (i.e. rain, fog), housing of the module and other factors.

For simple detection purposes (security applications e.g.) without the need of speed measurements, range may be enhanced by further reducing the IF bandwidth. With 250Hz bandwidth and a simple comparator, we get already a 20m detection range.

## Datasheet Revision History

Version	Date	Changes
1.0	Aug-2008	Preliminary release
1.1	Oct-2008	Replaced diagram FM characteristics
1.2	Apr-2009	Replaced Fig. 4. Changes dual 4 patch to single 4 patch antenna
1.3	May-2009	Fig. 1 changed blockdiagram
1.4	June-2009	Updated System diagram
1.5	May-2011	Cosmetic text correction
1.6	April-2014	Fig. 2 System diagram comments added
2.0	July-2014	New antenna design starting from production lot 1421. Better sensitivity.

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