DAC1401D125

Dual 14-bit DAC, up to 125 Msps

Rev. 01 — 13 November 2008 Product data sheet

1. General description

The DAC1401D125 is a dual port, high-speed, 2-channel CMOS Digital-to-Analog Converter (DAC), optimized for high dynamic performance with low power dissipation. Supporting an update rate of up to 125 Msps, the DAC1401D125 is suitable for Direct IF applications.

Separate write inputs allow data to be written to the two DAC ports independently of one another. Two separate clocks control the update rate of each DAC port.

The DAC1401D125 can interface two separate data ports or one single interleaved high-speed data port. In Interleaved mode, the input data stream is demultiplexed into its original I and Q data and latched. The I and Q data is then converted by the two DACs and updated at half the input data rate.

Each DAC port has a high-impedance differential current output, suitable for both single-ended and differential analog output configurations.

The DAC1401D125 is pin compatible with the AD9767, DAC2904 and DAC5672.

2. Features

- Dual 14-bit resolution
- 125 Msps update rate
- Single 3.3 V supply
- Dual-port or Interleaved data modes
- 1.8 V, 3.3 V and 5 V compatible digital inputs
- Internal and external reference
- 2 mA to 20 mA full-scale output current
- **Typical 185 mW power dissipation**
- 16 mW power-down
- SFDR: 81 dBc; f_o = 1 MHz; f_s = 52 Msps
- **SFDR: 79 dBc; f_o = 10.4 MHz; f_s = 78 Msps**
- SFDR: 75 dBc; f_o = 1 MHz; f_s = 52 Msps; –12 dBFS
- LQFP48 package
- Industrial temperature range of –40 °C to +85 °C

3. Applications

- Quadrature modulation
- Medical/test instrumentation
- Direct IF applications
- Direct digital frequency synthesis
- Arbitrary waveform generator

4. Ordering information

Table 1. Ordering information

Type number	Package		
	Name	Description	Version
DAC1401D125HL	LQFP48	plastic low profile quad flat package; 48 leads; body 7 × 7 × 1.4 mm	SOT313-2

5. Block diagram

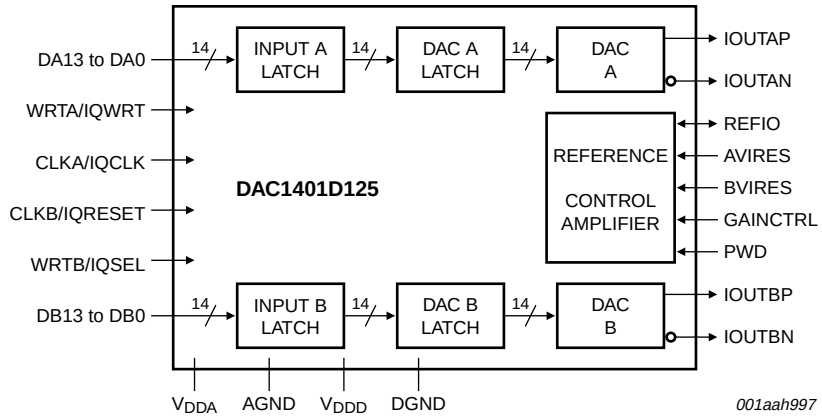


Fig 1. Block diagram

6. Pinning information

6.1 Pinning

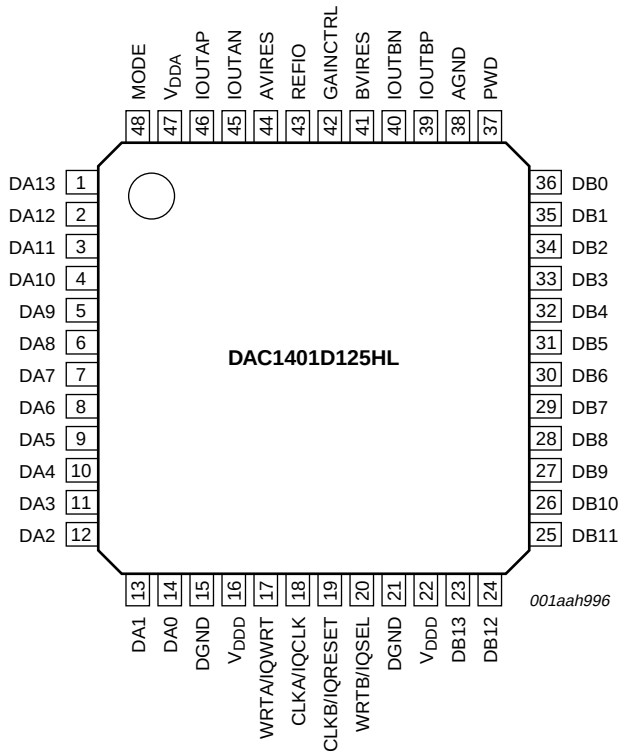


Fig 2. Pin configuration SOT313-2 (LQFP48)

6.2 Pin description

Table 2. Pin description

Symbol	Pin	Type[1]	Description
DA13	1	I	DAC A data input bit 13 (MSB)
DA12	2	I	DAC A data input bit 12
DA11	3	I	DAC A data input bit 11
DA10	4	I	DAC A data input bit 10
DA9	5	I	DAC A data input bit 9
DA8	6	I	DAC A data input bit 8
DA7	7	I	DAC A data input bit 7
DA6	8	I	DAC A data input bit 6
DA5	9	I	DAC A data input bit 5
DA4	10	I	DAC A data input bit 4
DA3	11	I	DAC A data input bit 3
DA2	12	I	DAC A data input bit 2
DA1	13	I	DAC A data input bit 1

Table 2. Pin description *...continued*

Symbol	Pin	Type[1]	Description
DA0	14	I	DAC A data input bit 0 (LSB)
DGND	15	G	digital ground
V_{DDD}	16	S	digital supply voltage
WRTA/IQWRT	17	I	Input write port A Input write IQ in Interleaved mode
CLKA/IQCLK	18	I	Input clock port A Input clock IQ in Interleaved mode
CLKB/IQRESET	19	I	Input clock port B reset IQ in Interleaved mode
WRTB/IQSEL	20	I	Input write port B select IQ in Interleaved mode
DGND	21	G	digital ground
V_{DDD}	22	S	digital supply voltage
DB13	23	I	DAC B data input bit 13 (MSB)
DB12	24	I	DAC B data input bit 12
DB11	25	I	DAC B data input bit 11
DB10	26	I	DAC B data input bit 10
DB9	27	I	DAC B data input bit 9
DB8	28	I	DAC B data input bit 8
DB7	29	I	DAC B data input bit 7
DB6	30	I	DAC B data input bit 6
DB5	31	I	DAC B data input bit 5
DB4	32	I	DAC B data input bit 4
DB3	33	I	DAC B data input bit 3
DB2	34	I	DAC B data input bit 2
DB1	35	I	DAC B data input bit 1
DB0	36	I	DAC B data input bit 0 (LSB)
PWD	37	I	Power-down mode
AGND	38	G	analog ground
IOUTBP	39	O	DAC B current output
IOUTBN	40	O	complementary DAC B current output
BVIRES	41	I	adjust DAC B for full-scale output current
GAINCTRL	42	I	gain control mode
REFIO	43	I/O	reference input/output
AVIRES	44	I	adjust DAC A for full-scale output current
IOUTAN	45	O	complementary DAC A current output
IOUTAP	46	O	DAC A current output
V_{DDA}	47	S	analog supply voltage
MODE	48	I	select between Dual port mode or Interleaved mode

[1] Type description: S = Supply; G = Ground; I = Input; O = Output; I/O = Input/Output.

7. Limiting values

Table 3. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V_{DDD}	digital supply voltage		[1]	–0.3	+5.0	V
V_{DDA}	analog supply voltage		[1]	–0.3	+5.0	V
ΔV_{DD}	supply voltage difference	between analog and digital supply voltage		–150	+150	mV
V_I	input voltage	digital inputs referenced to DGND		–0.3	+5.5	V
		pins REFIO, AVIRES, BVIRES referenced to AGND		–0.3	+5.5	V
V_O	output voltage	pins IOUTAP, IOUTAN, IOUTBP and IOUTBN referenced to AGND		–0.3	V_{DDA} + 0.3	V
T_{stg}	storage temperature			–55	+150	°C
T_{amb}	ambient temperature			–40	+85	°C
T_j	junction temperature			-	125	°C

[1] All supplies are connected together.

8. Thermal characteristics

Table 4. Thermal characteristics

Symbol	Parameter	Conditions	Typ	Unit
$R_{th(j-a)}$	thermal resistance from junction to ambient	in free air	89.3	K/W
$R_{th(c-a)}$	thermal resistance from case to ambient	in free air	60.6	K/W

9. Characteristics

Table 5. Characteristics

V_{DDD} = V_{DDA} = 3.3 V; AGND and DGND connected together; $I_{O(fs)}$ = 20 mA and T_{amb} = –40 °C to +85 °C; typical values measured at T_{amb} = 25 °C.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Supplies						
V_{DDD}	digital supply voltage		3.0	3.3	3.65	V
V_{DDA}	analog supply voltage		3.0	3.3	3.65	V
I_{DDD}	digital supply current	f_s = 65 Msps, f_o = 1 MHz, V_{DD} = 3.0 V to 3.6 V	-	6	7	mA
I_{DDA}	analog supply current	f_s = 65 Msps, f_o = 1 MHz, V_{DD} = 3.0 V to 3.6 V	-	50	65	mA
P_{tot}	total power dissipation	f_s = 65 Msps, f_o = 1 MHz, V_{DD} = 3.0 V to 3.6 V	-	185	260	mW
P_{pd}	power dissipation in power-down mode		-	16.5	-	mW
Digital inputs						
V_{IL}	LOW-level input voltage		DGND	-	0.9	V
V_{IH}	HIGH-level input voltage		1.3	-	V_{DDD}	V

Table 5. Characteristics *...continued*

V_{DDD} = V_{DDA} = 3.3 V; AGND and DGND connected together; $I_{O(fs)}$ = 20 mA and T_{amb} = −40 °C to +85 °C; typical values measured at T_{amb} = 25 °C.

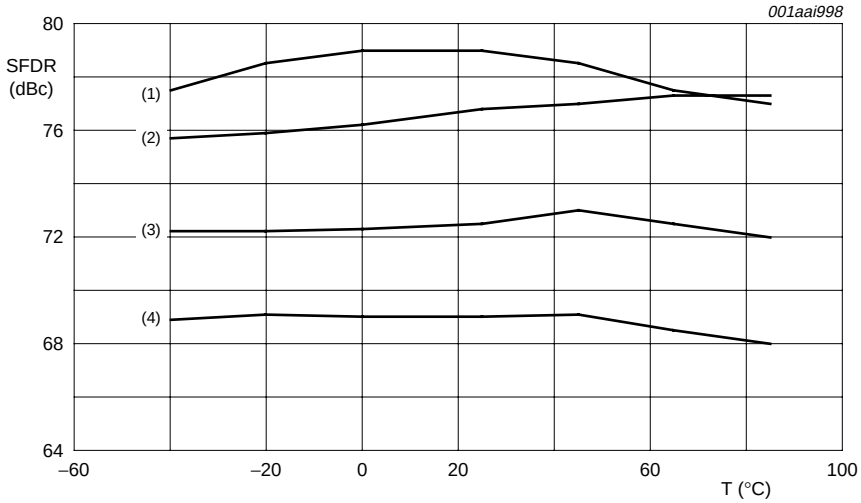
Symbol	Parameter	Conditions		Min	Typ	Max	Unit
I_{IL}	LOW-level input current	V_{IL} = 0.9 V		-	5	-	µA
I_{IH}	HIGH-level input current	V_{IH} = 1.3 V		-	5	-	µA
C_i	input capacitance		[1]	-	5	-	pF
Analog outputs (IOUTAP, IOUTAN, IOUTBP and IOUTBN)							
$I_{O(fs)}$	full-scale output current	differential outputs		2	-	20	mA
V_O	output voltage	compliance range	[1]	−1	-	+1.25	V
R_o	output resistance		[1]	-	150	-	kΩ
C_o	output capacitance		[1]	-	3	-	pF
Reference voltage input/output (REFIO)							
$V_{O(ref)}$	reference output voltage			1.25	1.26	1.27	V
$I_{O(ref)}$	reference output current		[1]	-	100	-	nA
V_i	input voltage	compliance range		1.0	-	1.26	V
R_i	input resistance			-	1	-	MΩ
Input timing see Figure 18							
f_s	sampling frequency			-	-	125	Msps
$t_{w(WRT)}$	WRT pulse width	pins WRTA, WRTB		2	-	-	ns
$t_{w(CLK)}$	CLK pulse width	pins CLKA, CLKB		2	-	-	ns
$t_{h(i)}$	input hold time			1	-	-	ns
$t_{su(i)}$	input set-up time			1.8	-	-	ns
Output timing (IOUTAP, IOUTAN, IOUTBP, IOUTBN)							
t_d	delay time				1	-	ns
t_t	transition time	rising or falling transition (10 % to 90 % or 90 % to 10 %)	[1]	-	0.6	-	ns
t_s	settling time	±1 LSB	[1]	-	43	-	ns
Static linearity							
INL	integral non-linearity	25 °C		±1.60	±2.15	±2.90	LSB
		−40 °C to +85 °C		±1.25	-	±2.95	LSB
DNL	differential non-linearity	−40 °C to +85 °C		±0.55	±0.75	±1.10	LSB
Static accuracy (relative to full-scale)							
E_{offset}	offset error			-0.02	-	+0.02	%
E_G	gain error	with external reference		-1.9	±1.5	+2.5	%
		with internal reference		-2.9	±2.1	+2.9	%
ΔG	gain mismatch	between DAC A and DAC B		-0.36	±0.05	+0.36	%

Table 5. Characteristics *...continued*

V_{DDD} = V_{DDA} = 3.3 V; AGND and DGND connected together; $I_{O(fs)}$ = 20 mA and T_{amb} = −40 °C to +85 °C; typical values measured at T_{amb} = 25 °C.

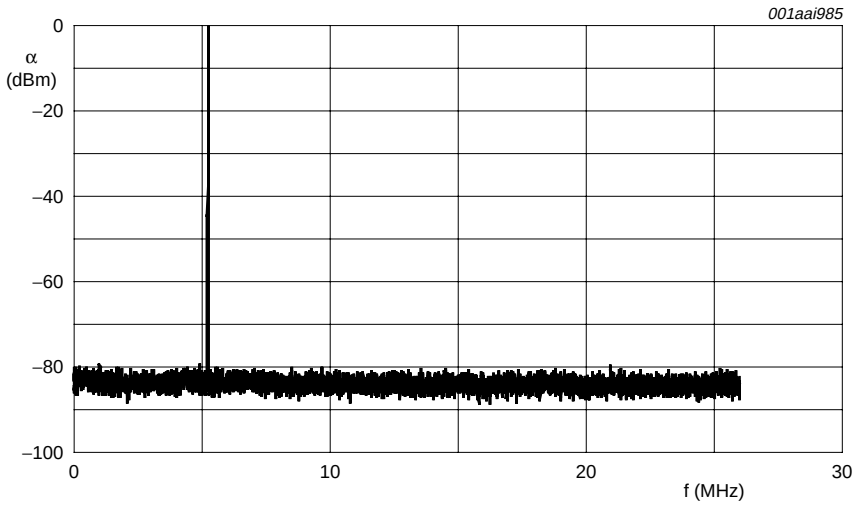
Symbol	Parameter	Conditions	Min	Typ	Max	Unit
Dynamic performance						
SFDR	spurious free dynamic range	B = Nyquist				
		f_s = 52 Msps; f_o = 1 MHz				
		0 dBFS	-	81	-	dBc
		−6 dBFS	-	80	-	dBc
		−12 dBFS	-	75	-	dBc
		f_s = 52 Msps; 0 dBFS				
		f_o = 5.24 MHz	-	79	-	dBc
		f_s = 78 Msps; 0 dBFS				
		f_o = 10.4 MHz	-	79	-	dBc
		f_o = 15.7 MHz	-	72	-	dBc
		f_s = 100 Msps; 0 dBFS				
		f_o = 5.04 MHz	-	77	-	dBc
		f_o = 20.2 MHz	61	69	-	dBc
		f_s = 125 Msps; 0 dBFS				
		f_o = 20.1 MHz	-	69	-	dBc
		Within a Window				
		f_s = 52 Msps; f_o = 1 MHz; 2 MHz span	-	90	-	dBc
		f_s = 52 Msps; f_o = 5.24 MHz; 10 MHz span	-	88	-	dBc
		f_s = 78 Msps; f_o = 5.26 MHz; 2 MHz span	-	92	-	dBc
		f_s = 125 Msps; f_o = 5.04 MHz; 10 MHz span	80	92	-	dBc
THD	total harmonic distortion	f_s = 52 Msps; f_o = 1 MHz	-	-79	-	dBc
		f_s = 78 Msps; f_o = 5.26 MHz	-	-76	-	dBc
		f_s = 100 Msps; f_o = 5.04 MHz	-	-75	-	dBc
		f_s = 125 Msps; f_o = 20.1 MHz	-	-65	-60	dBc
MTPR	multitone power ratio	f_s = 65 Msps; 2 MHz < f_o < 2.99 MHz; 8 tones at 110 kHz spacing at 0 dB full-scale	-	80	-	dBc
NSD	noise spectral density	f_s = 100 Msps; f_o = 5.04 MHz	-	-149	-	dBm/Hz
α_{cs}	channel separation	f_s = 78 Msps; f_o = 10.4 MHz	-	88.0	-	dBc
		f_s = 125 Msps; f_o = 20.1 MHz	-	83.5	-	dBc

[1] Guaranteed by design.

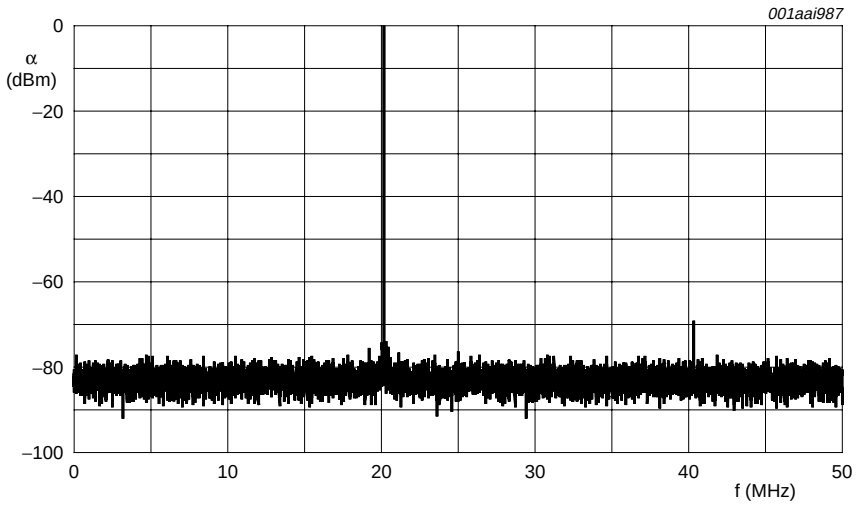


(1) f_o = 5 MHz
(2) f_o = 10 MHz
(3) f_o = 15 MHz
(4) f_o = 20 MHz

Fig 3. SFDR as a function of the ambient temperature at 125 Msps

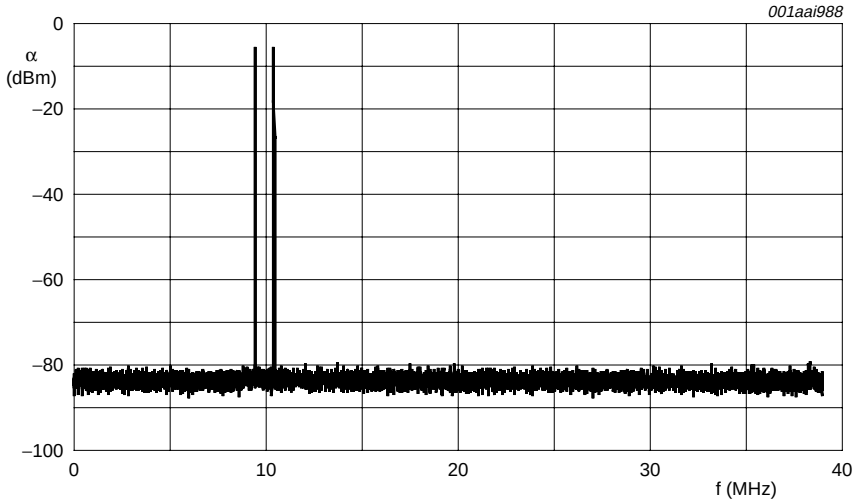


a. f_s = 52 Msps; f_c = 5.24 MHz; α = 0 dBFS



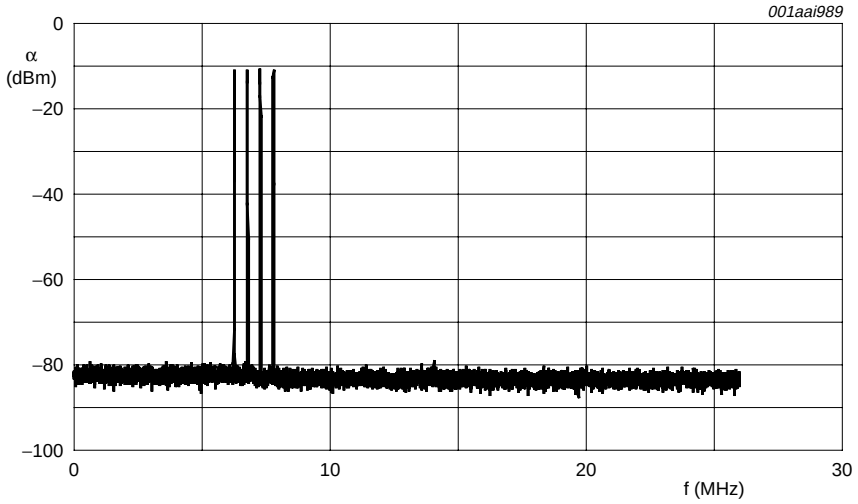
b. f_s = 100 Msps; f_c = 20 MHz; α = 0 dBFS

Fig 4. 1-tone SFDR



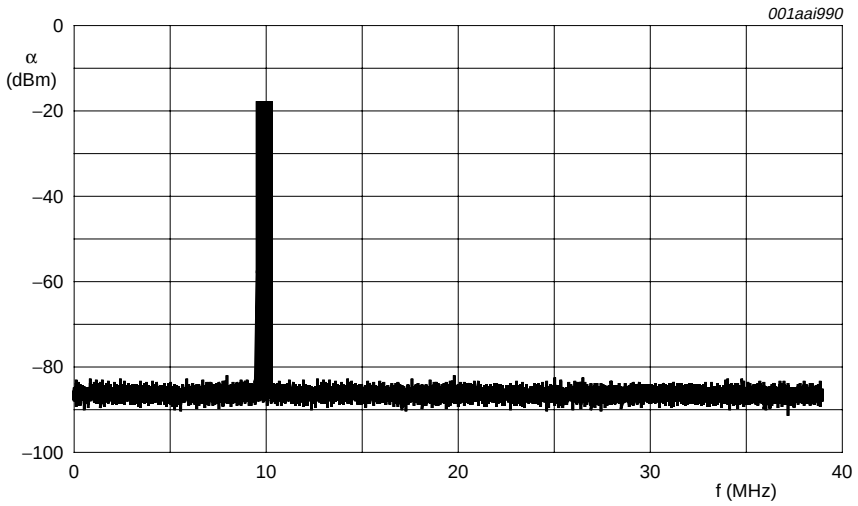
f_s = 78 Msps; f_c = 9.44 MHz, f_c = 10.44 MHz; α = 0 dBFS

Fig 5. 2-tone SFDR



f_s = 52 Msps; f_c = 6.25 MHz, f_c = 6.75 MHz; f_c = 7.25 MHz, f_c = 7.75 MHz; α = 0 dBFS

Fig 6. 4-tone SFDR



f_s = 78 Msps; from f_c = 9.5 MHz, 110 kHz spacing; α = 0 dBFS

Fig 7. 8-tone SFDR

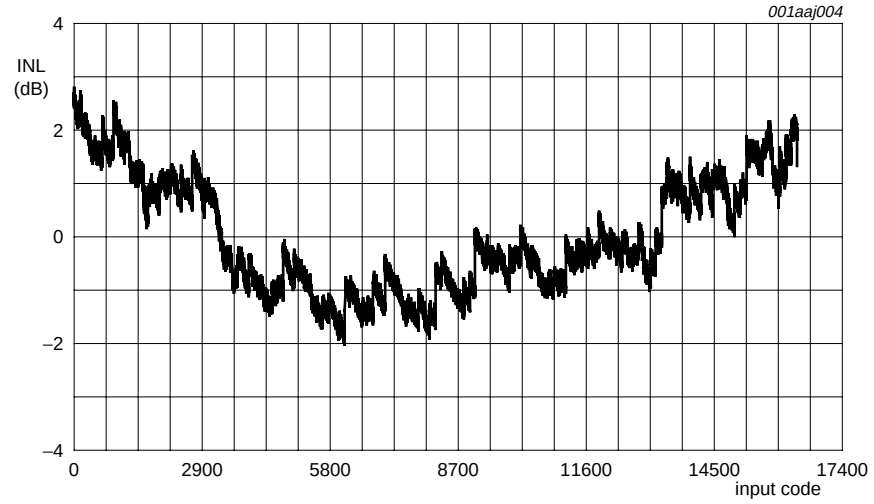


Fig 8. INL as a function of the input code

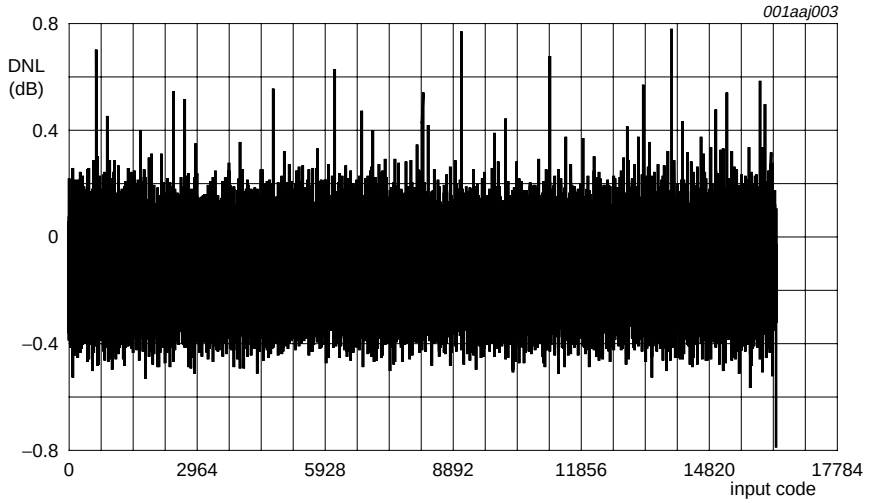
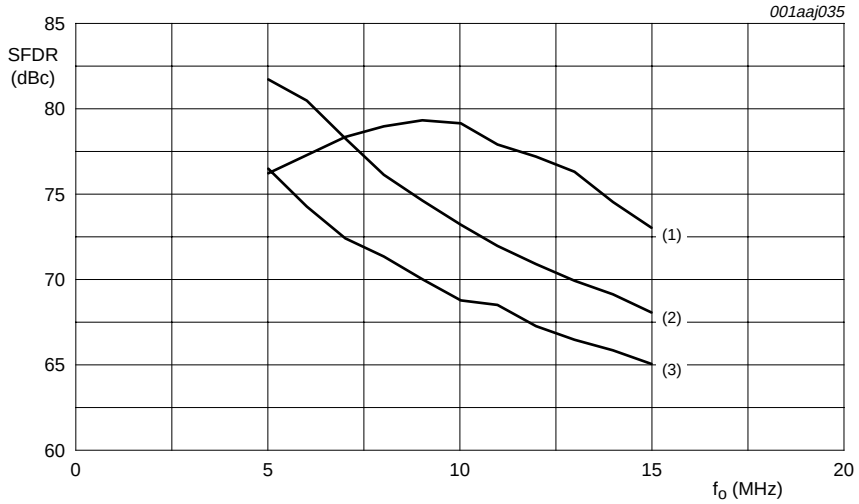


Fig 9. DNL as a function of the input code

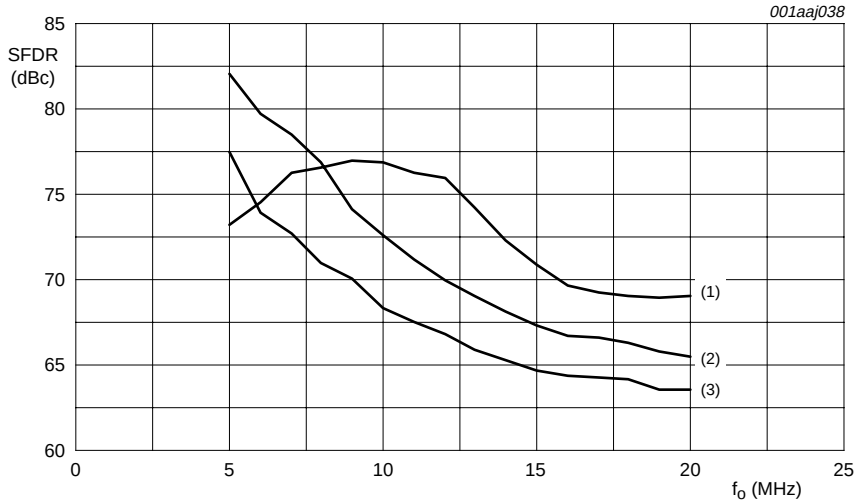


(1) f_o = 0 dBFS

(2) f_o = −6 dBFS

(3) f_o = −12 dBFS

Fig 10. SFDR full-scale at 78 Msps as a function of the output frequency

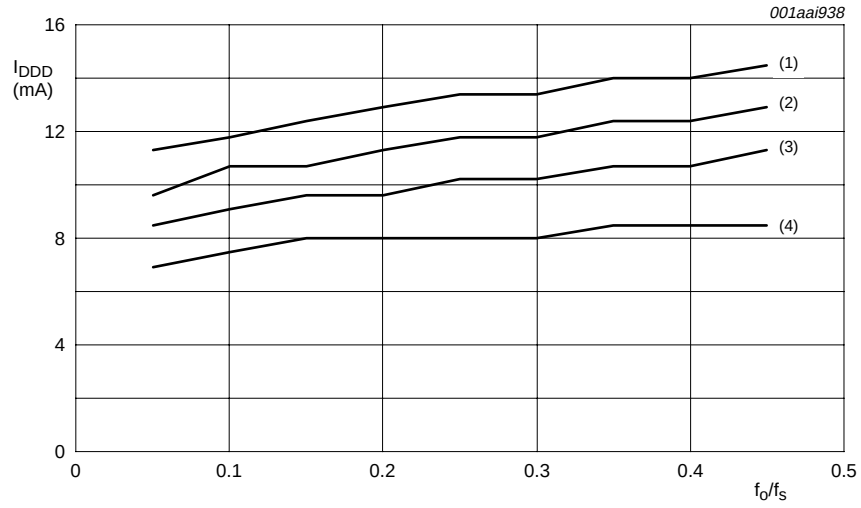


(1) f_o = 0 dBFS

(2) f_o = −6 dBFS

(3) f_o = −12 dBFS

Fig 11. SFDR full-scale at 125 Msps as a function of the output frequency



(1) f_s = 125 Msps

(2) f_s = 100 Msps

(3) f_s = 78 Msps

(4) f_s = 52 Msps

Fig 12. Digital supply current as a function of f_o/f_s

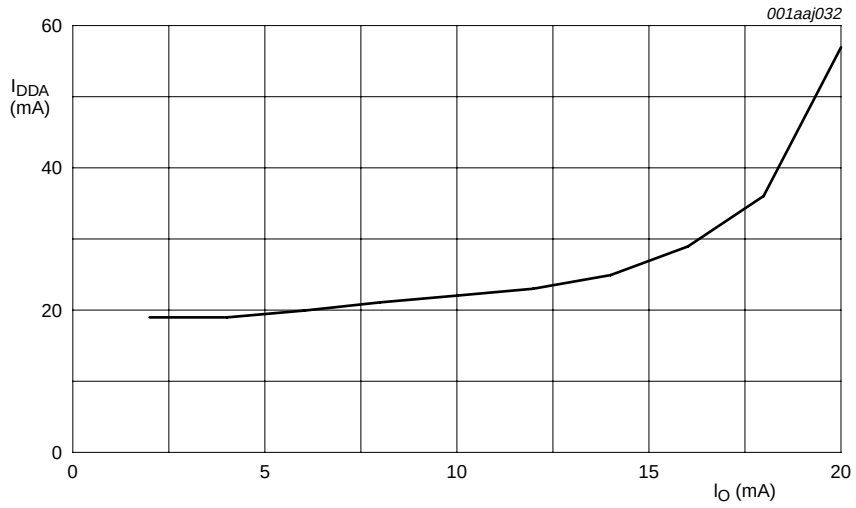


Fig 13. Analog supply current as a function of the output current

10. Application information

10.1 General description

The DAC1401D125 is a dual 14-bit DAC operating up to 125 Msps. Each DAC consists of a segmented architecture, comprising a 7-bit thermometer sub-DAC and a 7-bit binary weighted sub-DAC.

Two modes are available for the digital input depending on the status of the pin MODE. In Dual port mode, each DAC uses its own data input line at the same frequency as the update rate. In Interleaved mode, both DACs use the same data input line at twice the update rate.

Each DAC generates on pins IOUTAP/IOUTAN and IOUTBP/IOUTBN two complementary current outputs. This provides a full-scale output current ($I_{O(fs)}$), up to 20 mA. A single common or two independent full-scale current controls can be selected for both channels using pin GAINCTRL. An internal reference is available for the reference current which is externally adjustable using pin REFIO.

The DAC1401D125 operates at 3.3 V and has separate digital and analog power supplies. Pin PWD is used to power-down the device. The digital input is 1.8 V compliant, 3.3 V compliant and 5 V tolerant.

10.2 Input data

The DAC1401D125 input follows a straight binary coding where DA13 and DB13 are the Most Significant Bits (MSB) and DA0 and DB0 are the Least Significant Bits (LSB).

The setting applied to pin MODE defines whether the DAC1401D125 operates in Dual port mode or in Interleaved mode (see Table 6).

Table 6. Mode selection

Mode	Function	DA13 to DA0	DB13 to DB0	Pin 17	Pin 18	Pin 19	Pin 20
0	Interleaved mode	active	off	IQWRT	IQCLK	IQRESET	IQSEL
1	Dual port mode	active	active	WRTA	CLKA	CLKB	WRTB

10.2.1 Dual port mode

The data and clock circuit for Dual port mode operation is shown in Figure 14.

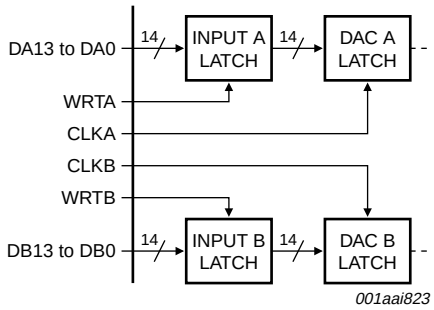


Fig 14. Dual port mode operation

Each DAC has its own independent data and clock inputs. The data enters the input latch on the rising edge of the WRTA/WRTB signal and is transferred to the DAC latch. The output is updated on the rising edge of the CLKA/CLKB signal.

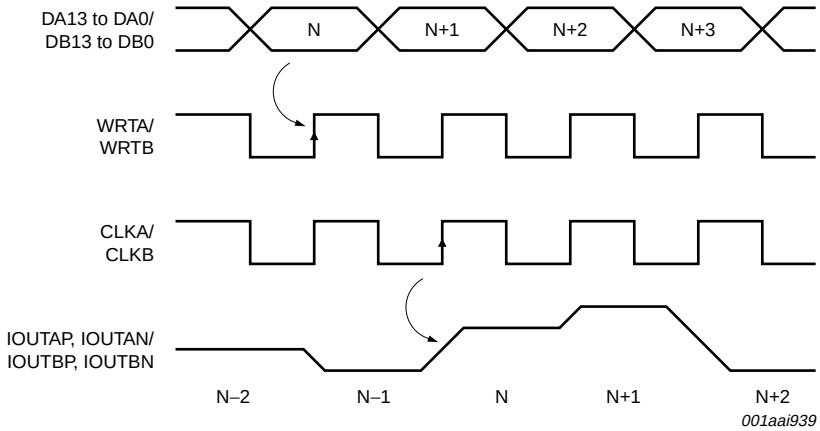


Fig 15. Dual port mode timing

10.2.2 Interleaved mode

The data and clock circuit for Interleaved mode operation is illustrated in Figure 16.

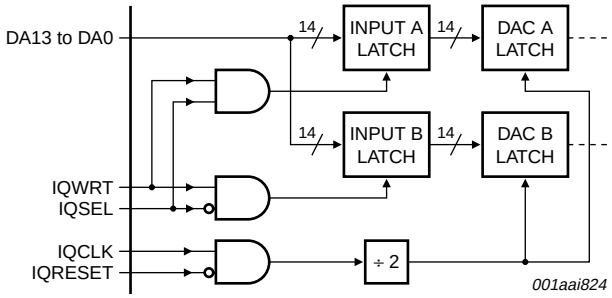


Fig 16. Interleaved mode

In Interleaved mode, both DACs use the same data and clock inputs at twice the update rate. Data enters the latch on the rising edge of IQWRT. The data is sent to either latch A or latch B, depending on the value of IQSEL. The IQSEL transition must occur when IQWRT and IQCLK are LOW.

The IQCLK is divided by 2 internally and the data is transferred to the DAC latch. It is updated on its rising edge. When IQRESET is HIGH, IQCLK is disabled, see Figure 17.

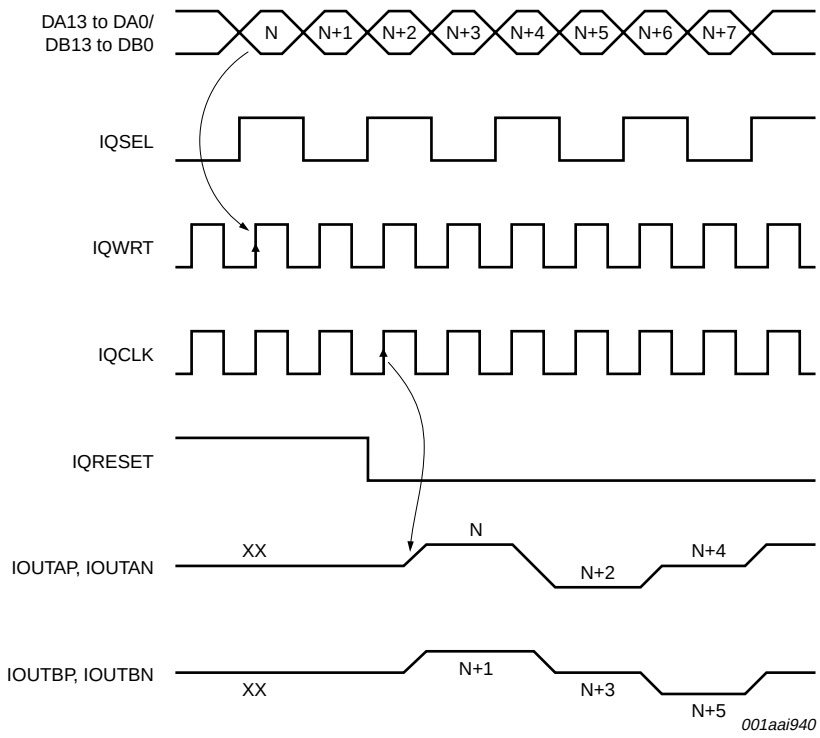


Fig 17. Interleaved mode timing

10.3 Timing

The DAC1401D125 can operate at an update rate up to 125 Msps. This generates an input data rate of 125 MHz in Dual port mode and 250 MHz in Interleaved mode. The timing of the DAC1401D125 is shown in Figure 18.

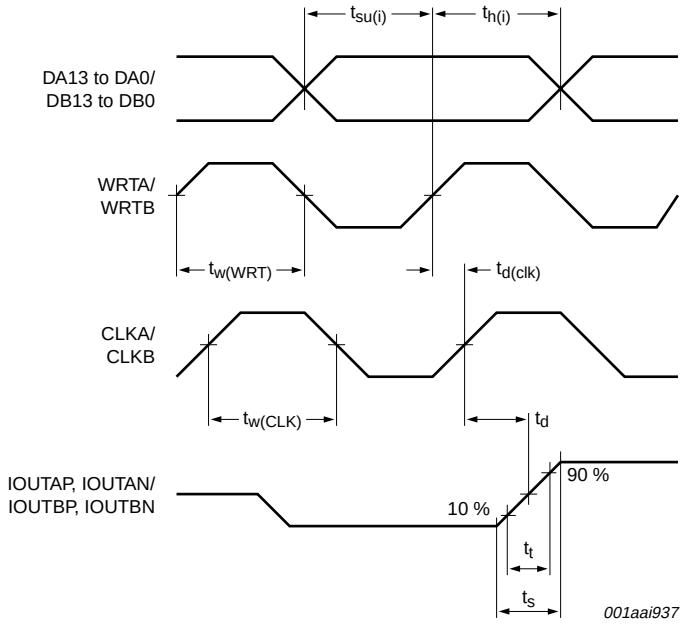


Fig 18. Timing of the DAC1401D125

The typical performances are measured at 50 % duty cycle but any timing within the limits of the characteristics will not alter the performance.

- A configuration resulting in the same timing for the signals WRTA/WRTB and CLKA/CLKB, can be achieved either by synchronizing them or by connecting them together.
- The rising edge of the CLKA/CLKB signal can also be placed in a range from half a period in front of the rising edge of the WRTA/WRTB signal to half a period minus 1 ns after the rising edge of the WRTA/WRTB signal.

A typical set-up time of 0 ns and a hold time of 0.6 ns enable the DAC1405D125 to be easily integrated into any application.

10.4 DAC transfer function

The full-scale output current for each DAC is the sum of the two complementary current outputs:

$$I_{O(fs)} = I_{IOUTP} + I_{IOUTN} \quad (1)$$

The output current depends on the digital input data:

$$I_{IOUTP} = I_{O(fs)} \times \left(\frac{DATA}{16384}\right) \qquad I_{IOUTN} = I_{O(fs)} \times \left(\frac{(16383 - DATA)}{16384}\right)$$

Table 7 shows the output current as a function of the input data, when $I_{O(fs)}$ = 20 mA.

Table 7. DAC transfer function

Data	DA13/DB13 to DA0/DB0	IOUTAP/IOUTBP	IOUTAN/IOUTBN
0	00 0000 0000 0000	0 mA	20 mA
...	...	...	...
8192	10 0000 0000 0000	10 mA	10 mA
...	...	...	...
16383	11 1111 1111 1111	20 mA	0 mA

10.5 Full-scale current adjustment

The DAC1401D125 integrates one 1.25 V reference and two current sources to adjust the full-scale current in both DACs.

The internal reference configuration is shown in Figure 19.

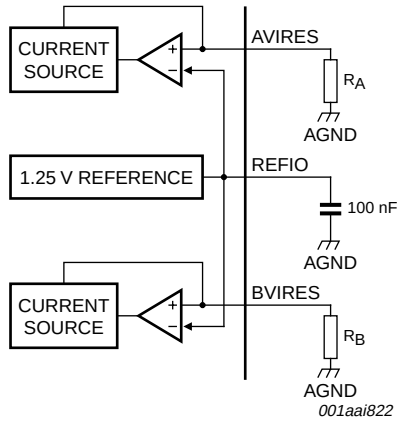


Fig 19. Internal reference configuration

The bias current is generated by the output of the internal regulator connected to the inverting input of the internal operational amplifiers. The external resistors R_A and R_B are connected to pins AVIRES and BVIRES, respectively. This configuration is optimal for temperature drift compensation because the bandgap can be matched with the voltage on the feedback resistors.

The relationship between full-scale output current ($I_{O(fs)}$) at the output of channel A or channel B and the resistor is:

$$I_{O(fs)} = \frac{24V_{REFIO}}{R_A} \quad (2)$$

The output current of the two DACs is typically fixed at 20 mA when both resistors R_A and R_B are set to 1.5 kΩ. The operational range of DAC1401D125 is from 2 mA to 20 mA.

It is recommended to decouple pin REFIO using a 100 nF capacitor.

An external reference can also be used for applications requiring higher accuracy or precise current adjustment. Due to the high input impedance of pin REFIO, applying an external source disables the bandgap.

10.6 Gain control

Table 8 shows how to select the different gain control modes.

Table 8. Gain control

GAINCTRL	Mode	DAC A full-scale control	DAC B full-scale control
0	independent gain control	AVIRES	BVIRES
1	common gain control	AVIRES	AVIRES

In Independent gain mode, both full-scale currents can be adjusted independently using resistors R_A on pin AVIRES and R_B on pin BVIRES.

In Common gain mode, both full-scale currents are adjusted with the same resistor and divided by two in both DACs.

10.7 Analog outputs

See Figure 20 for the analog output circuit of one DAC. This circuit consists of a parallel combination of PMOS current sources and associated switches for each segment.

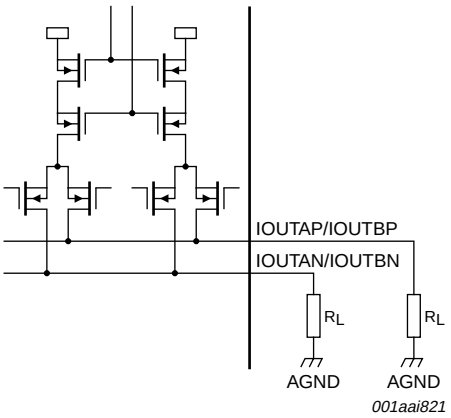


Fig 20. Equivalent analog output circuit

Cascode source configuration enables the output impedance of the source to be increased, thus improving the dynamic performance by reducing distortion.

The DAC1401D125 can be used either with:

- a differential output, coupled to a transformer (or operational amplifier) to reduce even-order harmonics and noise
- or a single-ended output for applications requiring unipolar voltage.

The typical configuration is to use 1 V p-p level on each output IOUTAP/IOUTBP and IOUTAN/IOUTBN but several combinations can be used as far as they respect the voltage compliance range.

10.7.1 Differential output using transformer

The use of a differentially coupled transformer output (see Figure 21) provides optimum distortion performance. In addition, it helps to match the impedance and provides electrical isolation.

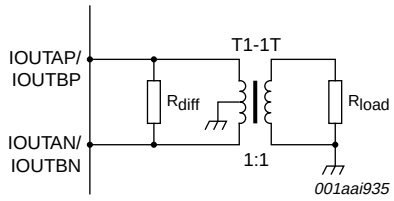


Fig 21. Differential output with transformer

The center tap is grounded to allow the DC current flow to/from both outputs. If the center tap is open, the differential resistor must be replaced by two resistors connected to ground.

10.7.2 Single-ended output

Using a single load resistor on one current output will provide an unipolar output range, typically from 0 V to 0.5 V with a 20 mA full-scale current at a 50 Ω load.

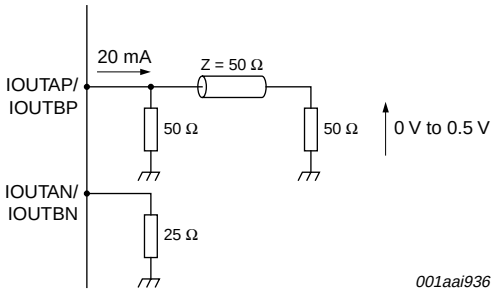


Fig 22. Single-ended output

The resistor on the other current output is 25 Ω.

10.8 Power-down function

The DAC1404D125 has a power-down function to reduce the power consumption when it is not active.

Table 9. Power-down

PWD	Device function	Power dissipation (typ)
0	active	185 mW
1	not active	16.5 mW

10.9 Alternative parts

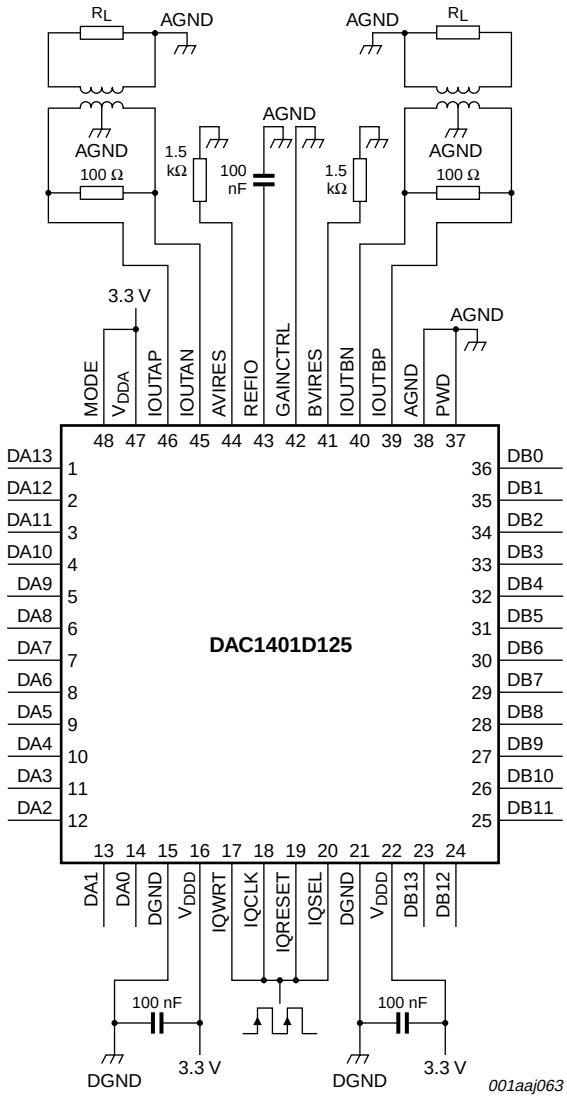
The following alternative parts are also available.

Table 10. Alternative parts

Pin compatible

Type number	Description	Sampling frequency
DAC1001D125	dual 10-bit DAC	up to 125 Msps
DAC1201D125	dual 12-bit DAC	up to 125 Msps

10.10 Application diagram



Dual port mode (MODE = 1)

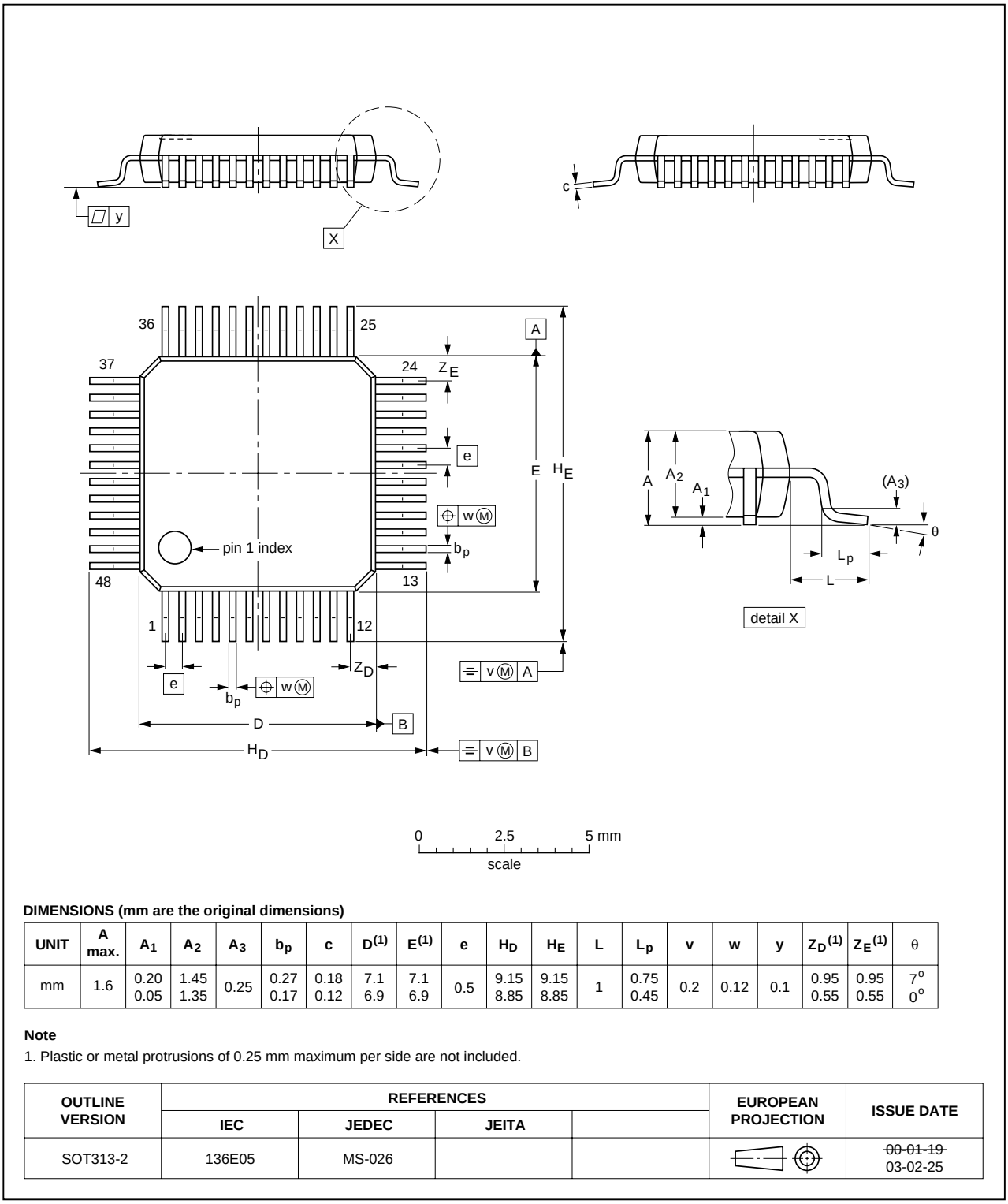
DAC active (PWD = 0)

Independent channel gain (GAINCTRL = 0)

Fig 23. Application diagram

11. Package outline

LQFP48: plastic low profile quad flat package; 48 leads; body 7 x 7 x 1.4 mm **SOT313-2**



DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A_1	A_2	A_3	b_p	c	$D^{(1)}$	$E^{(1)}$	e	H_D	H_E	L	L_p	v	w	y	$Z_D^{(1)}$	$Z_E^{(1)}$	θ
mm	1.6	0.20 0.05	1.45 1.35	0.25	0.27 0.17	0.18 0.12	7.1 6.9	7.1 6.9	0.5	9.15 8.85	9.15 8.85	1	0.75 0.45	0.2	0.12	0.1	0.95 0.55	0.95 0.55	7^o 0^o

Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT313-2	136E05	MS-026				~~00-01-19~~ 03-02-25

Fig 24. Package outline SOT313-2 (LQFP48)

12. Abbreviations

Table 11. Abbreviations

Acronym	Description
BW	BandWidth
DNL	Differential Non-Linearity
dBFS	deciBel Full-Scale
IF	Intermediate Frequency
INL	Integral Non-Linearity
LSB	Least Significant Bit
MSB	Most Significant Bit
PMOS	Positive-channel Metal-Oxide Semiconductor
SFDR	Spurious-Free Dynamic Range

13. Revision history

Table 12. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
DAC1401D125_1	20081113	Product data sheet	-	-

14. Legal information

14.1 Data sheet status

Document status[1][2]	Product status[3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL http://www.nxp.com.

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