

YIC



GPS & GLONASS Receiver Module YIC31009EBGG

Datasheet

Revision History

| Date | Reversion | Description |
|------------|-----------|------------------------------------|
| 2021/12/20 | 1.0 | First Draft, Based on YIC31009EBGG |
| | | |
| | | |

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1. Product Information

1.1 Product Description

YIC31009EBGG features high sensitivity, low power and ultra small form factor. The module is powered by GOKE, which provides superior sensitivity and performance even in urban canyon and dense foliage environment. The miniature size makes the module easy to integrate into portable device like mobile phone, PDAs, camera and vehicle locators.

Through the feature of 66-channel, the YIC31009EBGG boasts a hot start in less than 1 second. Innovative design and technology suppresses jamming sources and mitigates multipath effects, assisting excellent navigation performance.

Applications

- Automotive Navigation
- Personal Positioning
- Fleet Management
- Marine Navigation

1.2 Product Features

- Build on High Performance, Low-Power GOKE chipset
- Ultra High Track Sensitivity: -165dBm
- Built in High Gain LNA
- Extremely Fast TTFF at Low Signal Level
- NMEA-0183 Compliant Protocol or Custom Protocol
- RoHS Compliant

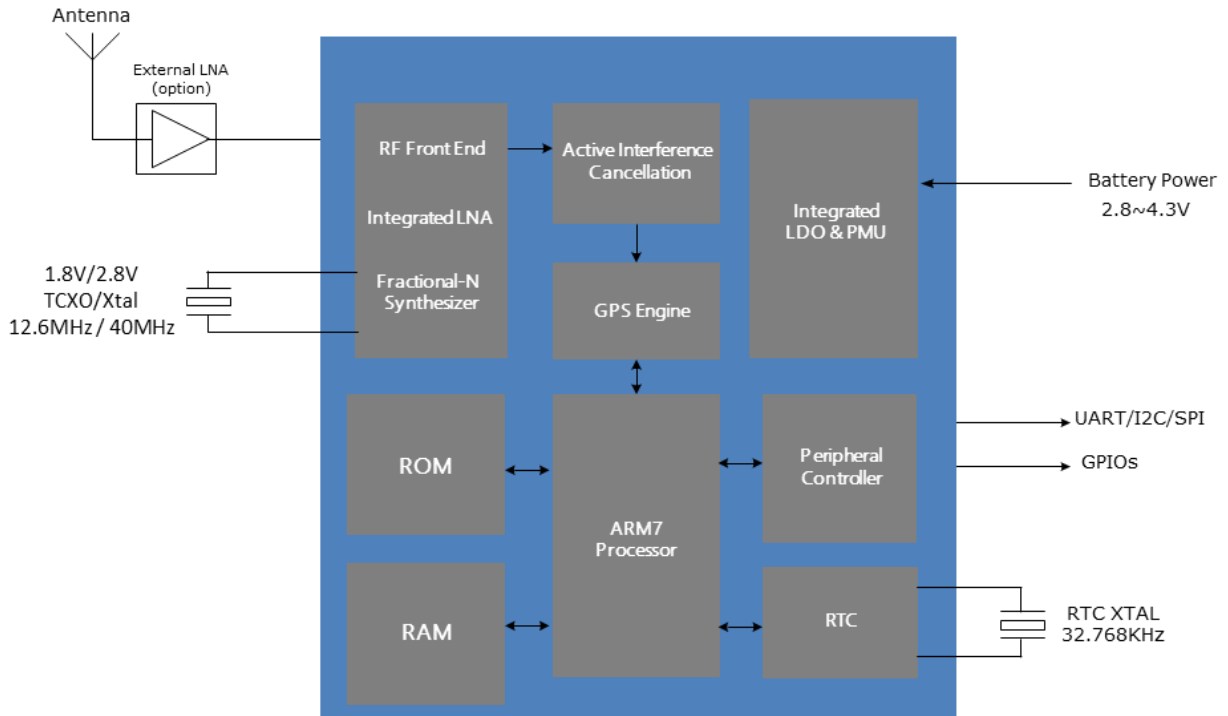
1.3 Product Specifications

| GPS Receiver | | |
|--------------------------|--|--|
| Chip | GOKE | |
| Frequency | Code 66 search channels, 22 synchronous tracking channels GPS&, QZSS, GALILEO: L1 1575.42MHz C/A GLONASS: L1OF 1602MHz BeiDou: B1 1561.098MHz SBAS: WAAS, EGNOS, MSAS, GAGAN | |
| Update Rate | 1Hz (default) , up to 10Hz | |
| Position Accuracy | Position | <2.5m CEP @-130 dBm |
| | Accuracy of 1PPS Signal | Typical accuracy: ±10ns / Time pulse width 100ms |
| | Acceleration Accuracy | Without aid: 0.1m/s ² |
| Startup Time | Cold start | 35s typ @-130dBm |
| | Warm start | 30s typ @-130dBm |
| | Hot start | 1s typ @-130dBm |
| Sensitivity | Acquisition | -148Bm |
| | Re-acquisition | -156Bm |
| | Tracking | -165dBm |
| GNSS Operating limit | Altitude | 18,000m |
| | Velocity | 515m/s |
| | Acceleration | 4G |
| Protocol Support | UART Port: TXD and RXD 9600bps (default), Baud rate supports 4800bps to 460800bps NMEA 0183 Protocol | |
| Environment | Operation temperature | -40°C ~ +85°C |
| | Storage temperature | -45°C ~ +125°C |
| Physical Characteristics | Size | 10.1±0.15 × 9.7±0.15 × 2.2±0.1mm |
| | Weight | Approx. 0.41g |

1.4 DC Electrical Characteristics

| Parameter | Min. | Typ. | Max. | Units |
|---------------------------------|------|------|------|-------|
| Input Voltage | 2.8 | 3.3 | 4.3 | Volt |
| Acquisition | | 38 | | mA |
| Tracking | | 36 | | mA |
| Backup Battery | | 20 | | uA |
| Low Level Output Voltage (VOL) | | | 0.4 | Volt |
| High Level Output Voltage (VOH) | 2.4 | | | Volt |
| Low Level Input Voltage (VIL) | | | 0.8 | Volt |
| High Level Input Voltage (VIH) | 2 | | | Volt |
| Low Level Output Current (IOL) | | 2 | | mA |
| High Level Output Current (IOH) | | 2 | | mA |

2. Block Diagram



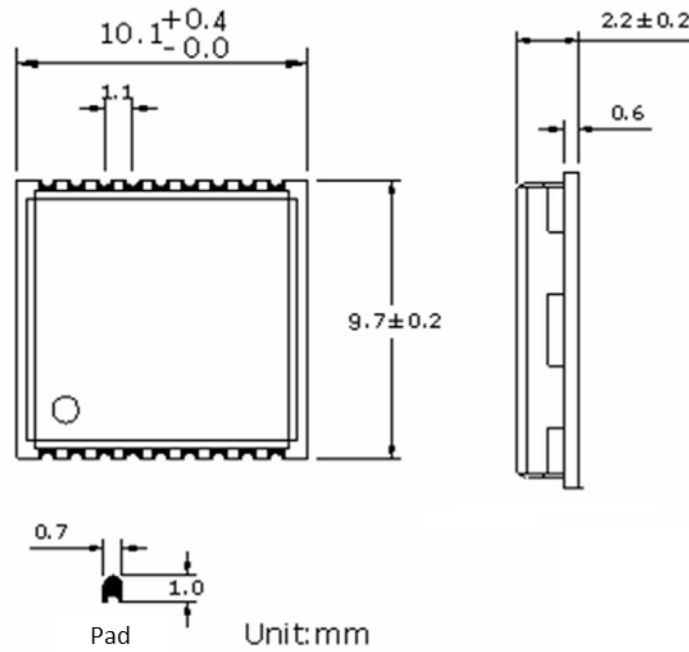
3. Module Pin Assignment

| YIC31009EBGG Top View | | | |
|--------------------------|--------|-------|---|
| 10 | GND | RESET | 9 |
| 11 | RF_IN | VCC | 8 |
| 12 | GND | NC | 7 |
| 13 | NC | VBAT | 6 |
| 14 | VCC_RF | GPIO0 | 5 |
| 15 | NC | PPS | 4 |
| 16 | TXB | RXA | 3 |
| 17 | RXB | TXA | 2 |
| 18 | GPIO1 | GND | 1 |

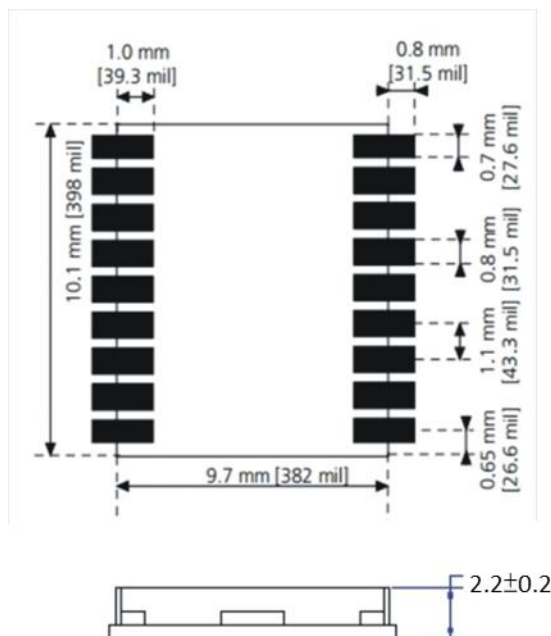
3.1 Pin Descriptions

| Pin NO. | Pin Name | Remark |
|---------|----------|--|
| 1 | GND | Ground |
| 2 | TXA | UART serial data output |
| 3 | RXA | UART serial data input |
| 4 | PPS | Time pulse (1PPS) (if not used, must be left floating) |
| 5 | GPIO0 | General purpose I/O |
| 6 | VBAT | Backup battery supply voltage |
| 7 | NC | No connection |
| 8 | VCC | Main power supply to the engine board |
| 9 | RESET | System reset |
| 10 | GND | Ground |
| 11 | RF_IN | RF signal input |
| 12 | GND | Ground |
| 13 | NC | No connection |
| 14 | VCC_RF | Output power supply for external LNA or active antenna |
| 15 | NC | No connection |
| 16 | TXB | UART serial data output |
| 17 | RXB | UART serial data input |
| 18 | GPIO1 | General purpose I/O |

4. Dimensions



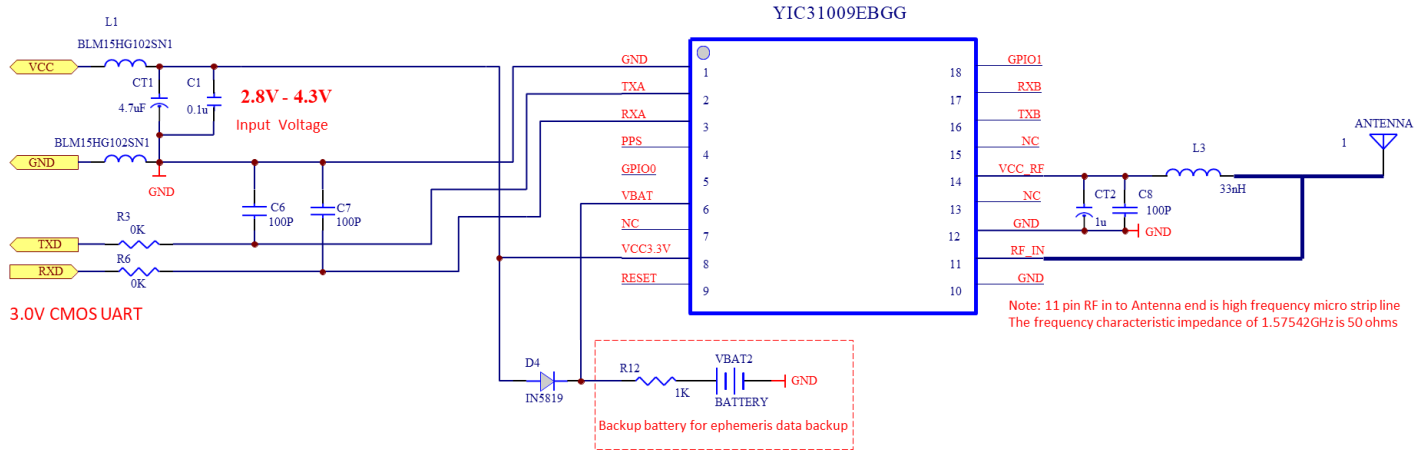
5. Recommended Footprint



unit: mm
Tolerance: ± 0.1

6. Application Circuit

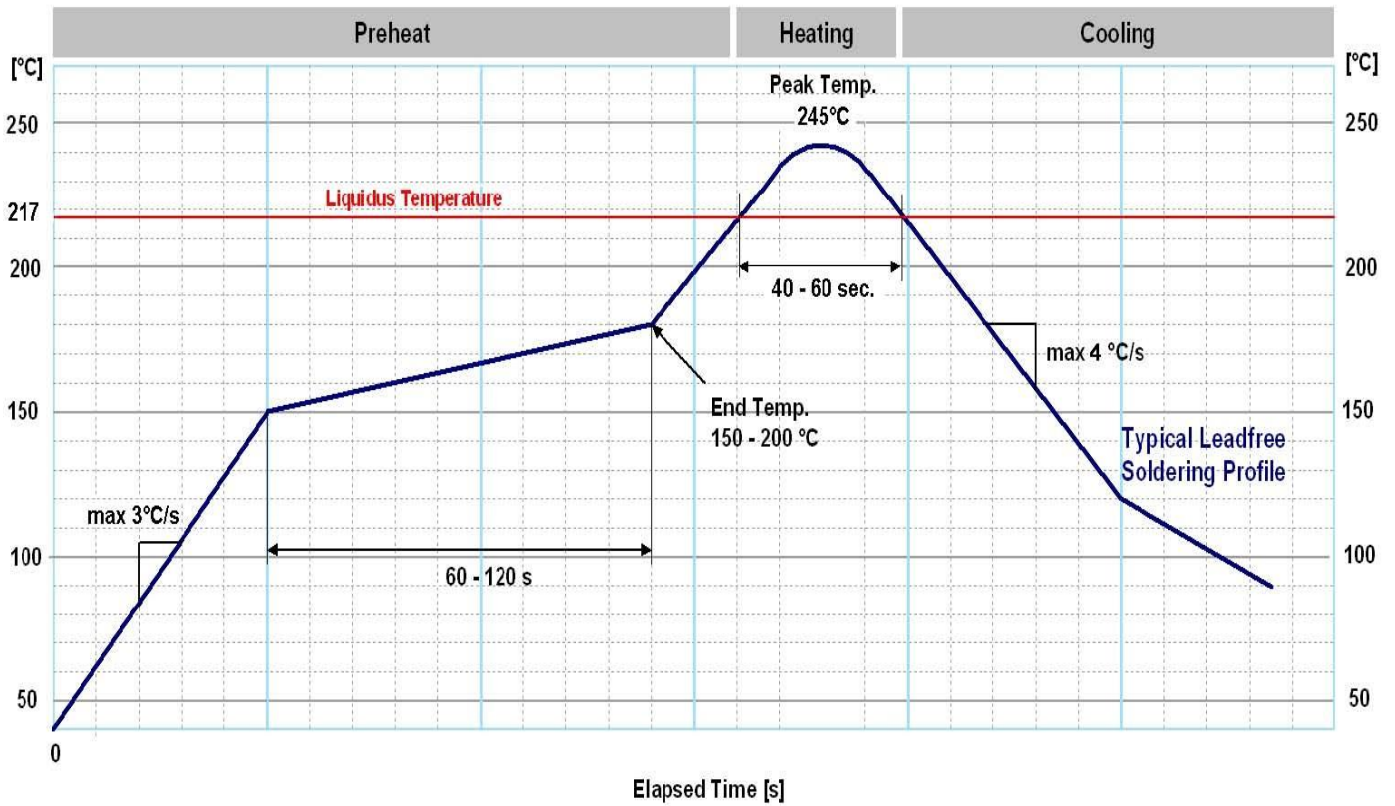
6.1 Application Circuit of YIC31009EBGG



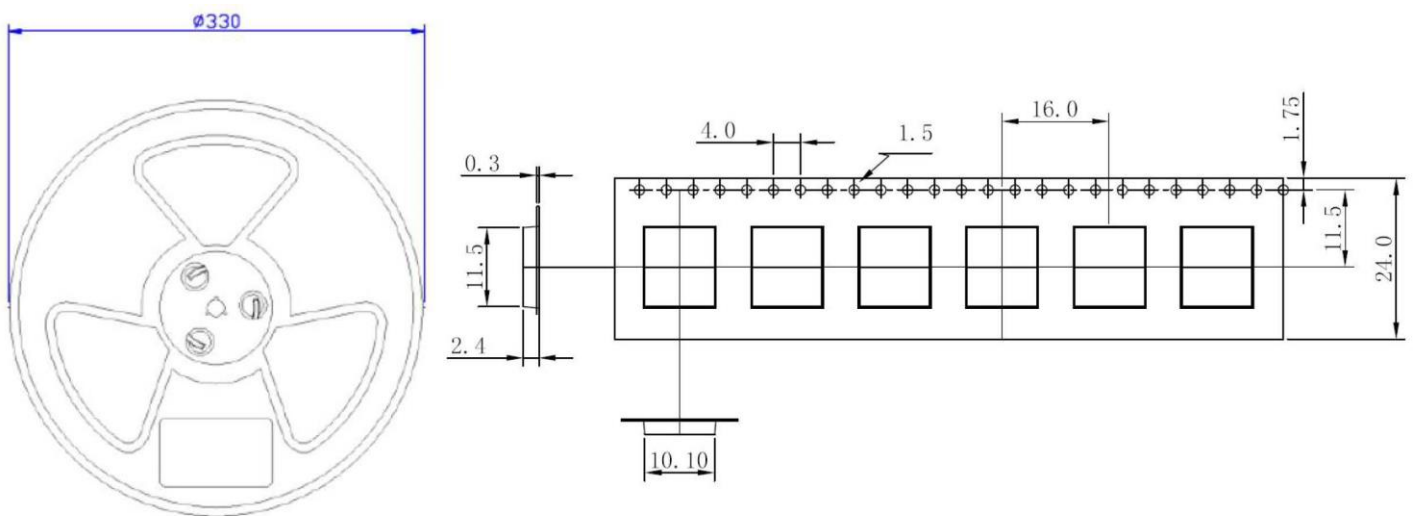
6.2 Layout Notes

1. A decoupling capacitor should be placed close to VDD pin of the module, and the width of power routing should be more than 0.5mm.
2. The characteristic impedance of RF routing between RF port to antenna should be controlled to 50 Ω .
3. Do not place the module close to any EMI source, RF routing, clock signal or other high-frequency switching signal, etc.

7. Reflow Profile



8. Tape & Reel



9. Software Interface

| NMEA | Description |
|------|--|
| GGA | GGA Global positioning system fixed data |
| GLL | GLL Geographic position—latitude/longitude |
| GSA | GNSS DOP and active satellites |
| GSV | GNSS satellites in view |
| RMC | RMC Recommended minimum specific GNSS data |
| VTG | VTG Course over ground and ground speed |

10. Protocol

10.1 GGA – Global Positioning System Fix Data

For example:

\$xxGGA, 161229.487,3723.2475,N, 12158.3416,W, 1,07,1.0,9.0,M.0000*18

| Field | Name | Example | Units | Description |
|-------|------------------------|------------|--------|-----------------------------------|
| 1 | Message ID | \$xxGGA | | GGA protocol header |
| 2 | UTC Position | 161229.487 | | hhmmss.sss |
| 3 | Latitude | 3723.2457 | | ddmm.mmmm |
| 4 | N/S indicator | N | | N=north or S=south |
| 5 | Longitude | 12158.3416 | | dddmm.mmmm |
| 6 | E/W Indicator | W | | E=east or W=west |
| 7 | Position Fix Indicator | 1 | | See Table 10.1-1 |
| 8 | Satellites Used | 07 | | Range 0 to 12 |
| 9 | HDOP | 1.0 | | Horizontal Dilution of Precision |
| 10 | MSL Altitude | 9.0 | meters | |
| 11 | Units | M | meters | |
| 12 | Geoids Separation | | meters | |
| 13 | Units | M | meters | |
| 14 | Age of Diff.Corr. | | second | Null fields when DGPS is not Used |
| 15 | Diff.Ref.Station ID | 0000 | | |
| 16 | Check sum | *18 | | |
| 18 | <CR> <LF> | | | End of message termination |

Table 10.1-1 Position Fix Indicators

| Value | Description |
|-------|---|
| 0 | Fix not available or invalid |
| 1 | GPS & Glonass SPS Mode, fix valid |
| 2 | Differential GPS & Glonass, SPS Mode, fix valid |
| 3 | GPS & Glonass PPS Mode, fix valid |

10.2 GLL – Latitude/Longitude

For example:

\$xxGLL , 3723.2475, N,12158.3416, W,161229.487, A*2C

| Field | Name | Example | Units | Description |
|-------|---------------|------------|-------|----------------------------------|
| 1 | Message ID | \$xxGLL | | GLL protocol header |
| 2 | Latitude | 3723.2475 | | ddmm.mmmm |
| 3 | N/S Indicator | N | | N=north or S=south |
| 4 | Longitude | 12158.3416 | | dddmm.mmmm |
| 5 | E/W Indicator | W | | E=east or W=west |
| 6 | UTC Position | 161229.487 | | hhmmss.sss |
| 7 | Status | A | | A=data valid or V=data not valid |
| 8 | Check sum | *2C | | |
| 9 | <CR> <LF> | | | End of message termination |

10.3 GSA – GPS & GLONASS DOP and Active Satellites

For example:

\$xxGSA , A, 3, 07, 02, 26,27, 09, 04,15, , , , , , 1.8,1.0,1.5*33

| Field | Name | Example | Units | Description |
|-------|----------------|---------|-------|----------------------------------|
| 1 | Message | \$xxGSA | | GSA protocol header |
| 2 | Mode 1 | A | | See Table 10.3-1 |
| 3 | Mode 2 | 3 | | See Table 10.3-2 |
| 4 | Satellite Used | 07 | | Sv on Channel 1 |
| 5 | Satellite Used | 02 | | Sv on Channel 2 |
| 6 | ... | ... | | ... |
| 7 | Satellite Used | | | Sv on Channel 66 |
| 8 | PDOP | 1.8 | | Position Dilution of Precision |
| 9 | HDOP | 1.0 | | Horizontal Dilution of Precision |
| 10 | VDOP | 1.5 | | Vertical Dilution of Precision |
| 11 | Check sum | *33 | | |
| 12 | <CR> <LF> | | | End of message termination |

Table 10.3-1 Mode 1

| Value | Description |
|-------|-------------------|
| 1 | Fix not available |
| 2 | 2D |
| 3 | 3D |

Table 10.3-2 Mode2

| Value | Description |
|-------|---|
| M | Manual-forced to operate in 2D or 3D mode |
| A | Automatic-allowed to automatically switch 2D/3D |

10.4 GSV – GPS & GLONASS Satellites in View

For example :

\$xxGSV , 2, 1, 07, 07, 79,048, 42, 02, 51,062, 43, 26, 36,256, 42, 27, 27, 138,42*71

\$xxGSV, 2, 2, 07, 09, 23,313, 42, 04, 19, 159, 41, 15,12,041, 42*41.

| Field | Name | Example | Units | Description |
|-------|--------------------|---------|---------|--------------------------------------|
| 1 | Message ID | \$xxGSV | | GSV protocol header |
| 2 | Number of Message | 2 | | Range 1 to 3 |
| 3 | Message Number | 1 | | Range 1 to 3 |
| 4 | Satellites in View | 07 | | |
| 5 | Satellite ID | 07 | | Channel 1(Range 1 to 66) |
| 6 | Elevation | 79 | degrees | Channel 1(Maximum 90) |
| 7 | Azinmuth | 048 | degrees | Channel 1(True, Range 0 to 359) |
| 8 | SNR(C/NO) | 42 | dBHz | Range 0 to 99,null when not tracking |
| 9 | ... | | | ... |
| 10 | Satellite ID | 27 | | Channel 4(Range 1 to 66) |
| 11 | Elevation | 27 | degrees | Channel 1(Maximum 90) |
| 12 | Azimuth | 138 | degrees | Channel 1(True, Range 0 to 359) |
| 13 | SNR(C/NO) | 42 | dBHz | Range 0 to 99,null when not tracking |
| 14 | Check sum | *71 | | |
| 15 | <CR> <LF> | | | End of message termination |

10.5 RMC – Recommended Minimum Specific GNSS Data

For example:

\$xxRMC, 161229.487, A, 3723.2475, N, 12158.3416, W, 0.13,309.62, 120598,, *10

| Field | Name | Example | Units | Description |
|-------|--------------------|------------|---------|----------------------------------|
| 1 | Message ID | \$xxRMC | | RMC protocol header |
| 2 | UTS Position | 161229.487 | | hhmmss.sss |
| 3 | Status | A | | A=data valid or V=data not valid |
| 4 | Latitude | 3723.2475 | | ddmm.mmmm |
| 5 | N/S Indicator | N | | N=north or S=south |
| 6 | Longitude | 12158.3416 | | dddmm.mmmm |
| 7 | E/W Indicator | W | | E=east or W=west |
| 8 | Speed Over Ground | 0.13 | Knots | |
| 9 | Course Over | 309.62 | Degrees | True |
| 10 | Ground | | | |
| 11 | Date | 120598 | | Dummy |
| 12 | Magnetic variation | | Degrees | E=east or W=west |
| 13 | Check sum | *10 | | |
| 14 | <CR> <LF> End of | | | End of message termination |

10.6 VTG – Course Over Ground and Ground Speed

For example:

\$xxVTG, 309.62, T, M, 0.13, N, 0.2, K*6E

| Field | Name | Example | Units | Description |
|-------|------------|---------|---------|----------------------------|
| 1 | Message ID | \$xxVTG | | VTG protocol header |
| 2 | Course | 309.62 | Degrees | Measured heading |
| 3 | Reference | T | | True |
| 4 | Course | | Degrees | Measured heading |
| 5 | Reference | M | | Magnetic |
| 6 | Speed | 0.13 | Knots | Measured horizontal speed |
| 7 | Units | N | | Knots |
| 8 | Speed | 0.2 | Km/hr | Measured horizontal speed |
| 9 | Units | K | | Kilometer per hour |
| 10 | Check sum | *6E | | |
| 11 | <CR> <LF> | | | End of message termination |